

A Simplified, Empirical Large Signal Model for SiC MESFETs

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Outline

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- Model Description
 - Drain current
 - Parasitics
- Experimental Verification
 - S-parameters measurements
 - Harmonic power measurements
- Conclusions

Background

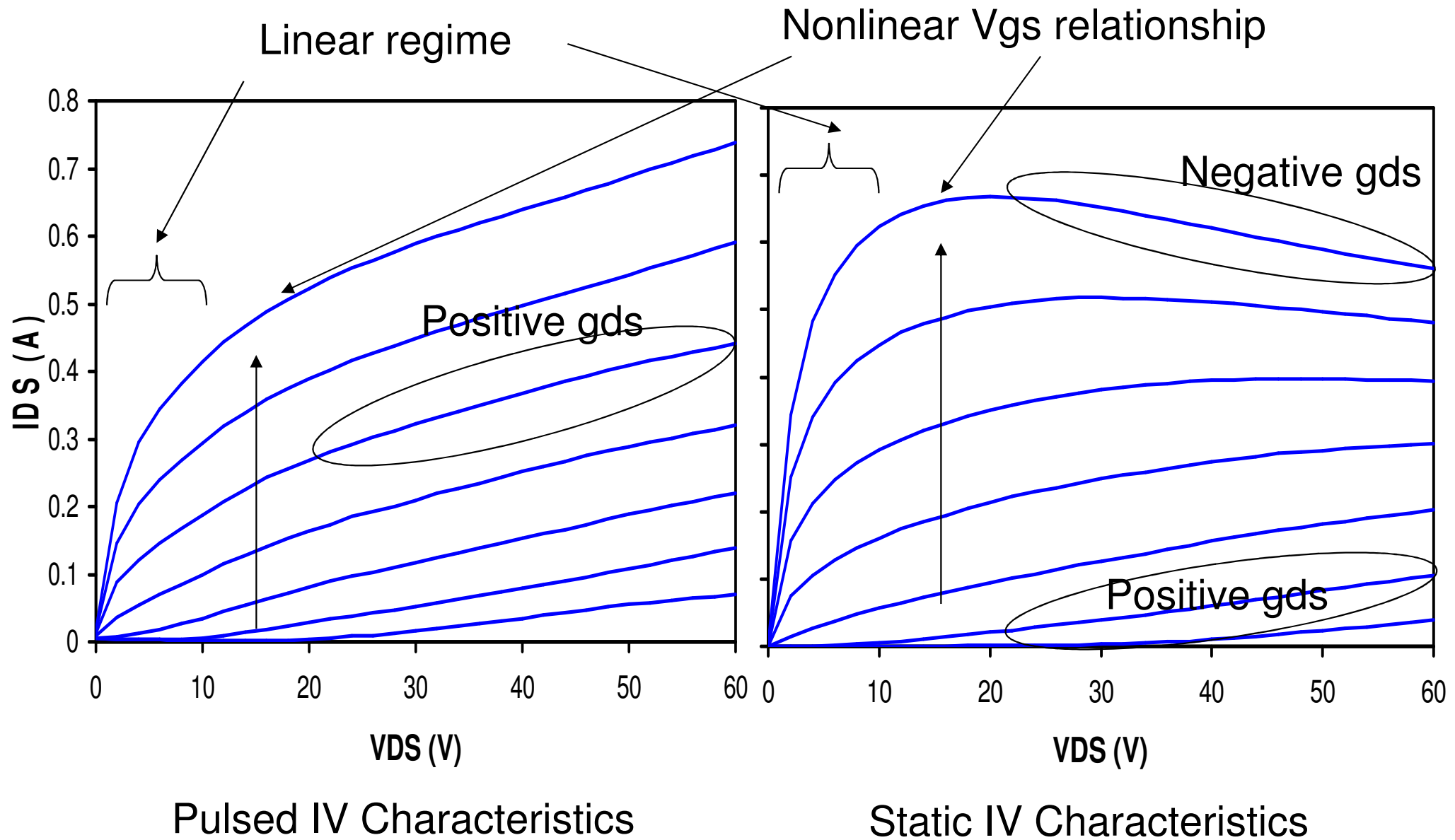
- Growing interest in wide bandgap semiconductor technologies (SiC and GaN)
- SiC technology features
 - High breakdown voltage → high RF power output
 - High power density → Self-heating effects
- Applications: PAs , mixers, oscillators ...
- Large-signal CAD model is important
- This Work
 - Cree CRF-24010 10W SiC MESFET



Objectives

- Develop an accurate empirical large-signal model capable of predicting
 - IV characteristics
 - Small signal S-parameters
 - Harmonic power for the first three harmonics
- Challenges
 - Obtaining accurate characterization of the device
 - Handling IV current dispersion “drooping” effects
 - Extracting intrinsic and extrinsic parasitics
 - Modeling output and input reflected harmonics
 - Minimizing model complexity

Elements of Pulsed and Static IV



Drain Current Model

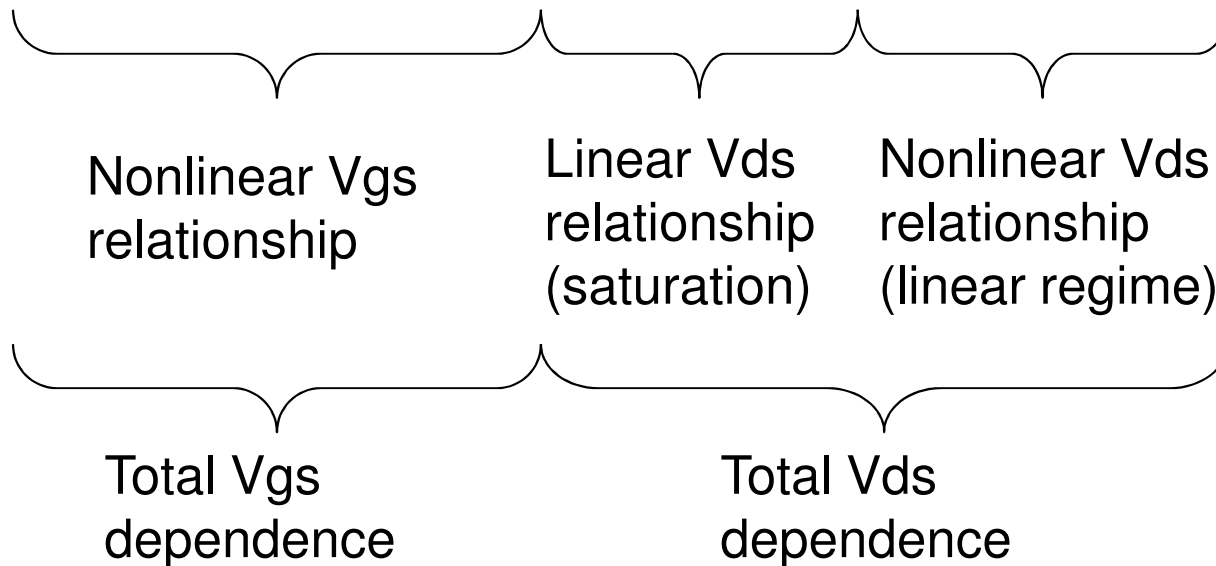
- How do we handle high power current dispersion?
- Use pulsed IV characteristics (PIV)
 - Resemble static IV curves of low power devices
 - Use known models with success
 - Only good for one bias → not for general purpose model
 - Static characteristics may be important (class A bias)
- Modify existing drain current models
 - Add dedicated parameters to account for dispersive behavior
 - Increased complexity. Parameters may not be fully exploited.
- In this work
 - Reformulate drain current equation using known mathematical modeling techniques
 - Develop mathematical model with variable order → model IV characteristics of variable complexity

Original Chalmer's Model

- Chalmer's model

$$\psi = P_1(V_{gs} - V_{pk}) + P_2(V_{gs} - V_{pk})^2 + P_3(V_{gs} - V_{pk})^3 \dots$$

$$I_{ds} = I_{pk}(1 + \tanh(\psi))(1 + \lambda V_{ds})\tanh(\alpha V_{ds})$$



- Assumes influence of V_{gs} and V_{ds} on I_{ds} are separable
- Assumes g_{mpk} occurs at the same V_{gs} independent of V_{ds}

Drain Current Equation

- Drain current equation for this model

$$I_{ds} = I_{pk} (1 + \tanh(\psi))$$

$$\psi = P_1 (V_{gs} - V_{pk}) + P_2 (V_{gs} - V_{pk})^2 + P_3 (V_{gs} - V_{pk})^3 \dots$$

$$P_1 = Q_{01} + Q_{11} (V_{ds}) + Q_{21} (V_{ds})^2 + Q_{31} (V_{ds})^3 \dots$$

$$P_2 = Q_{02} + Q_{12} (V_{ds}) + Q_{22} (V_{ds})^2 + Q_{32} (V_{ds})^3 \dots$$

$$P_3 = Q_{03} + Q_{13} (V_{ds}) + Q_{23} (V_{ds})^2 + Q_{33} (V_{ds})^3 \dots$$

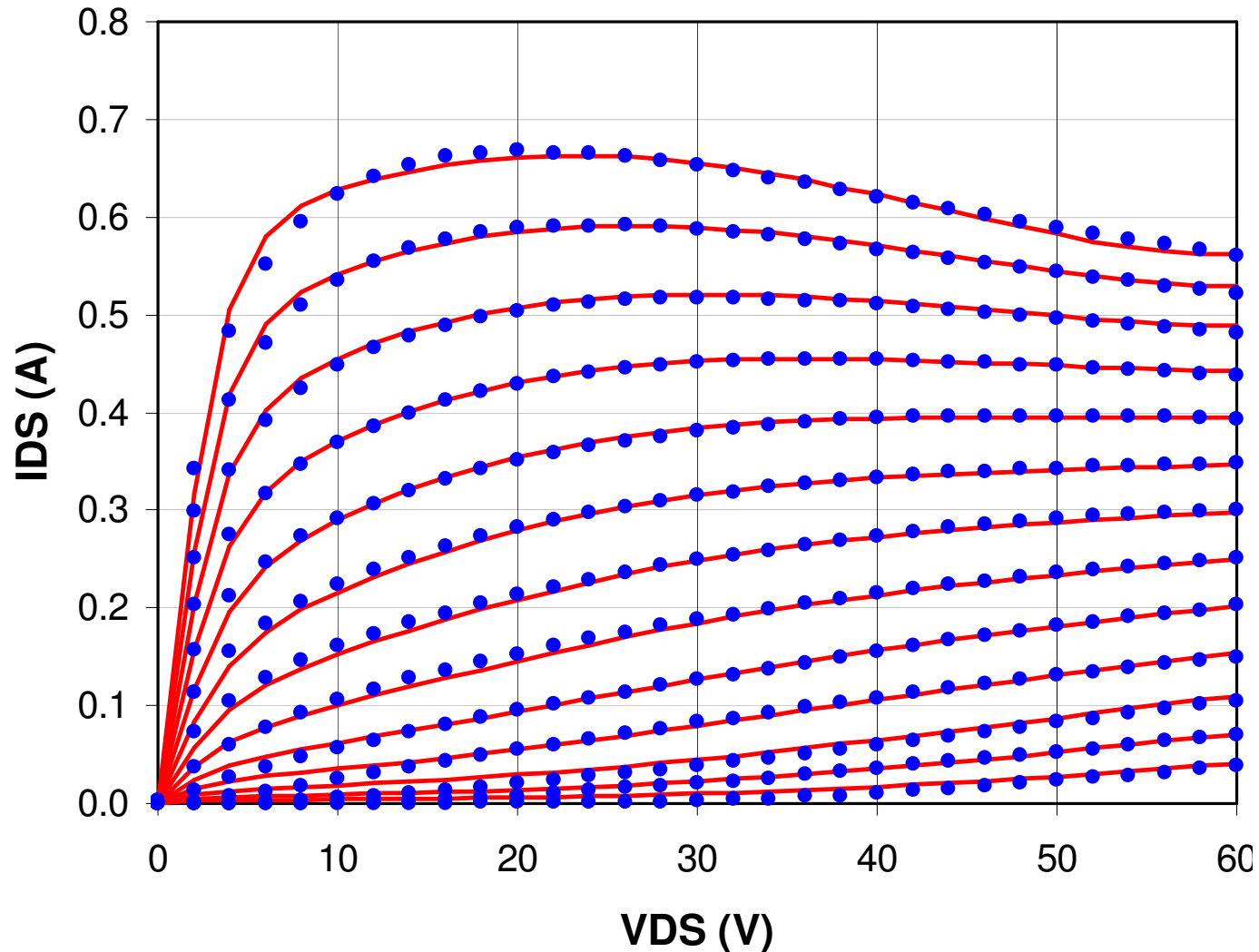
⋮

- Use Chalmer's method to describe V_{gs} nonlinearity
- Coefficients P_n are each a power series of V_{ds}
- Since g_{mpk} , I_{pk} , V_{pk} not constant across V_{ds} , use power series to track P_n across V_{ds}
- Effects of V_{gs} and V_{ds} are not treated as separable

Drain Current Equation Advantages

- Polynomials
 - Easy to implement, coefficients easy to determine
 - Differentiable
 - Mathematical order can be configured
 - Linear channel length effects (low order)
 - Nonlinear channel length effects (high order)
- Chalmer's method for V_{gs} relationship \rightarrow P2 is eliminated
- Possible elimination of $\tanh(\alpha V_{ds})$ term
 - linear region no different from saturation region if g_{mpk} , V_{pk} and I_{pk} modeled correctly
 - g_{mpk} , V_{pk} and I_{pk} difficult to model at low V_{ds}
- Purely electrical characterization of I_{ds}
 - No physical or temperature varying parameters

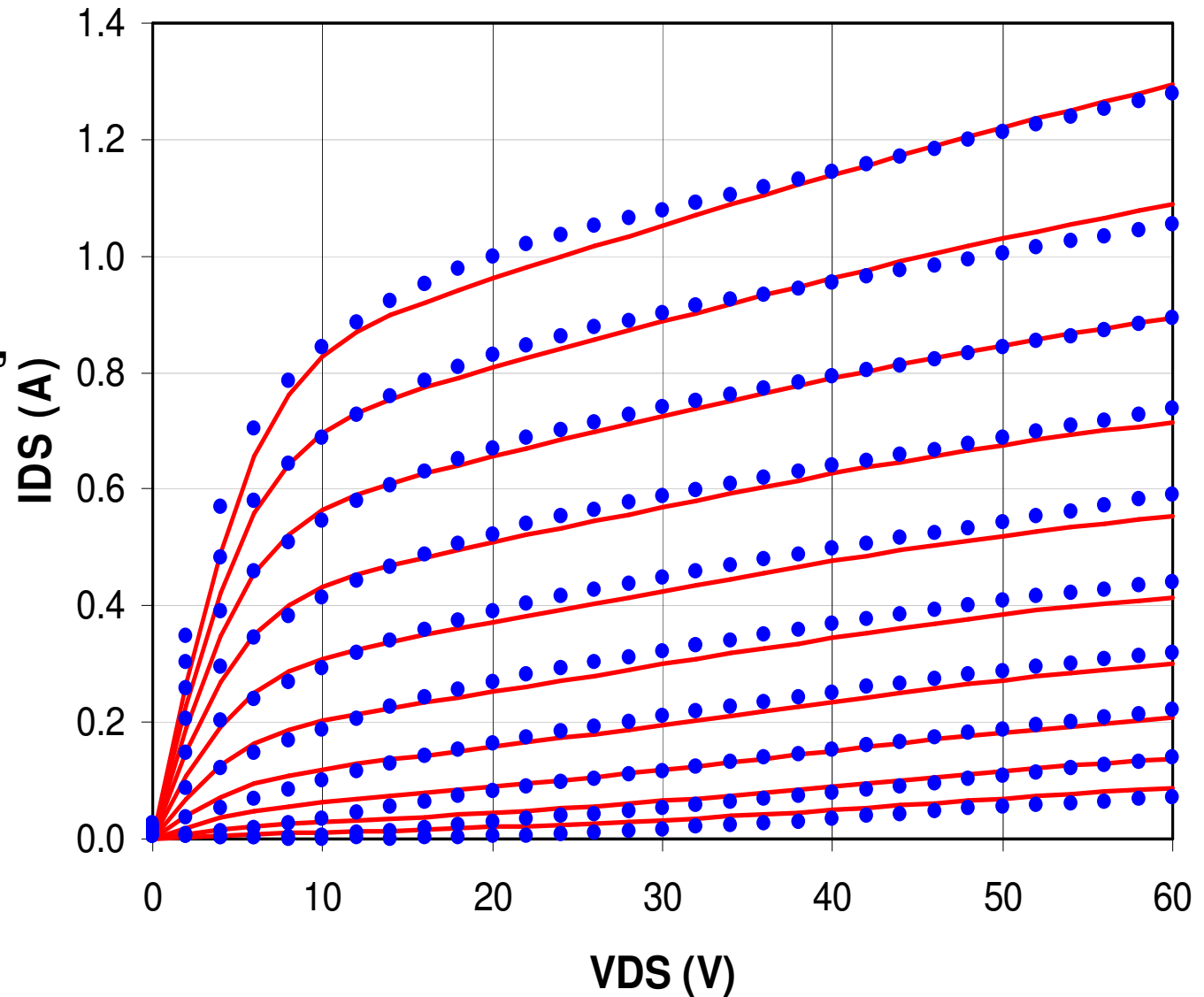
Drain Current Model – Static IV



- $V_{gs} = -10.0\text{V}$ to -4.0V , 0.5V steps, $V_{ds} = 0\text{V}$ to 60V , 2V steps
- Accurate modeling of complex static characteristics

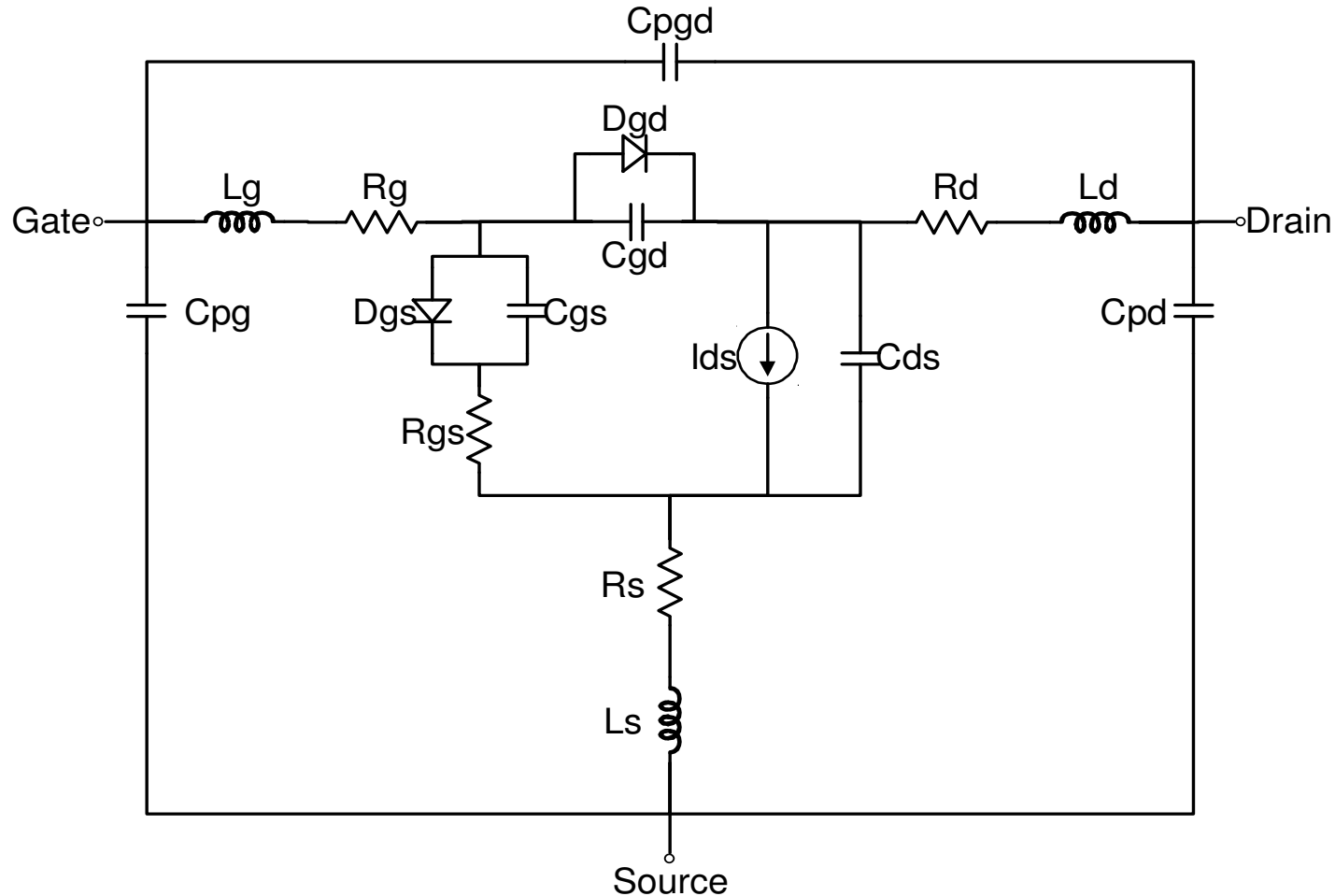
Drain Current Model – Pulsed IV

- Pulsed IV data using Auriga DIVA (Nanometrics)
- Same math form, variable order allows modeling of PIV
- $\tanh(\alpha V_{ds})$ improves linear regime fit
- PIV drain current model used in large-signal model



$V_{GS} = -10V$ to $1V$, $1V$ steps, $V_{DS} = 0V$ to $60V$, $2V$ steps

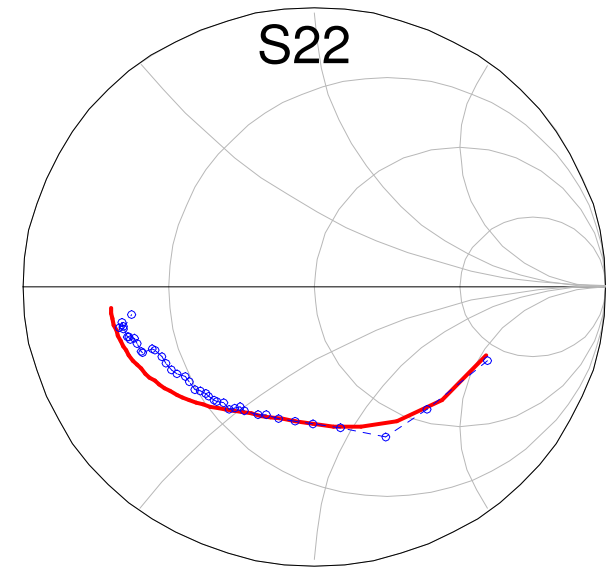
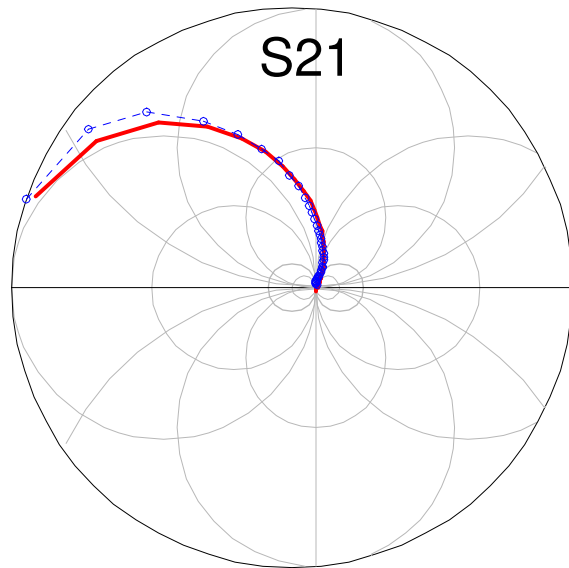
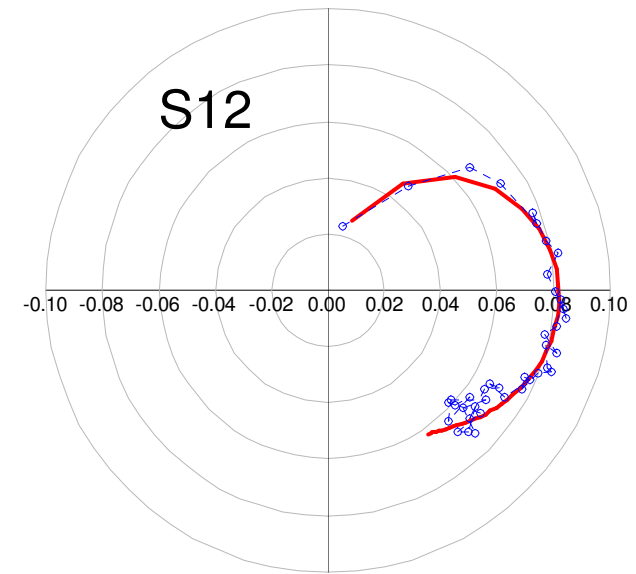
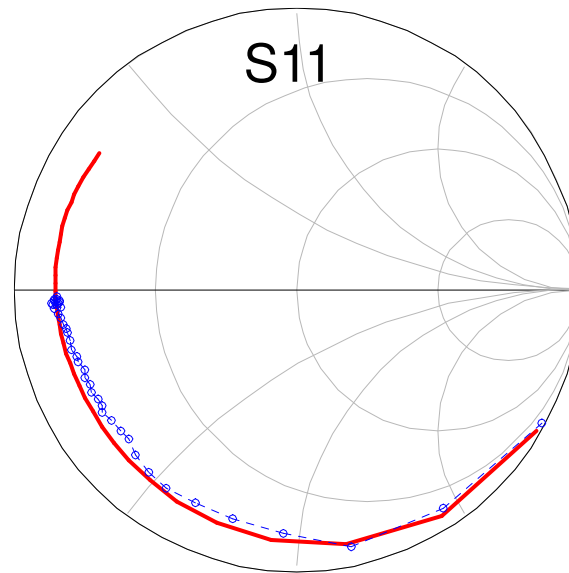
Complete Model with Parasitics



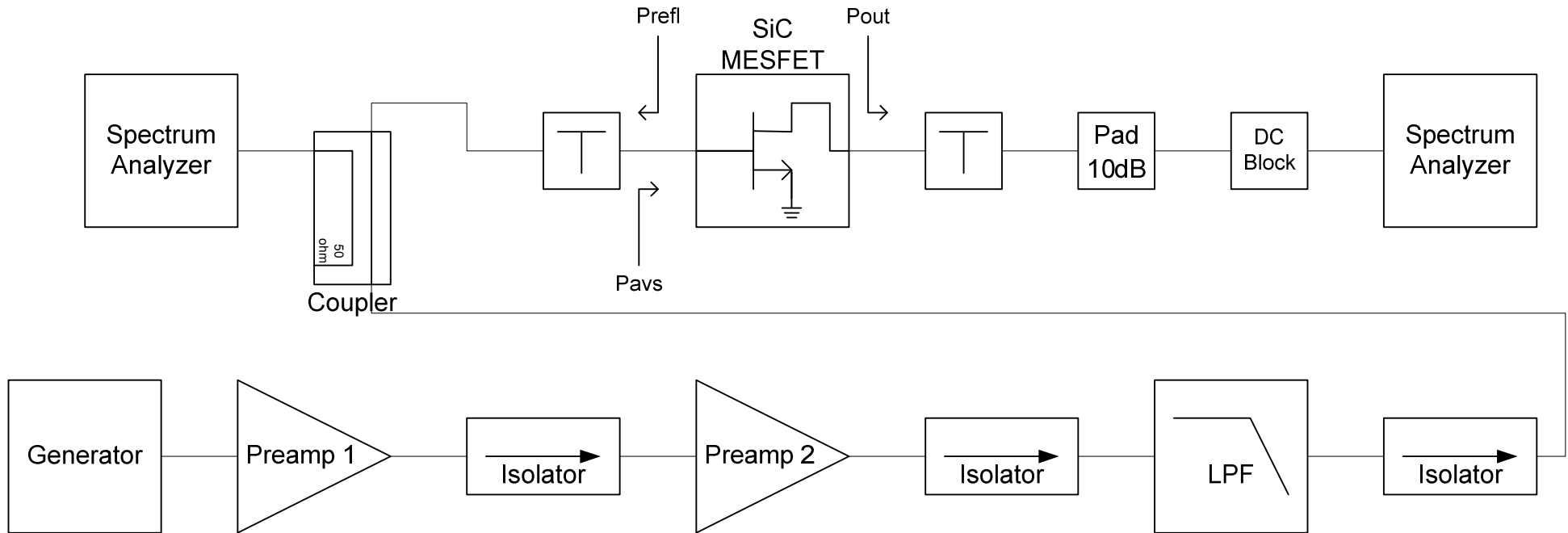
- Uses standard large-signal model topology → Simple
- Parasitics extracted from S-parameter measurements
- I_{ds} parameters optimized with parasitic resistances
- Nonlinear caps modeled with Chalmer's charge eqs

S-parameter Verification

- Cree CRF-24010 biased at $V_{DS}=48.0V$
 $I_{DS}=500mA$
- Frequency range 0.1GHz to 4.0GHz at -5dBm source
- Good agreement with measured data
- Supplemental RF current generator not needed

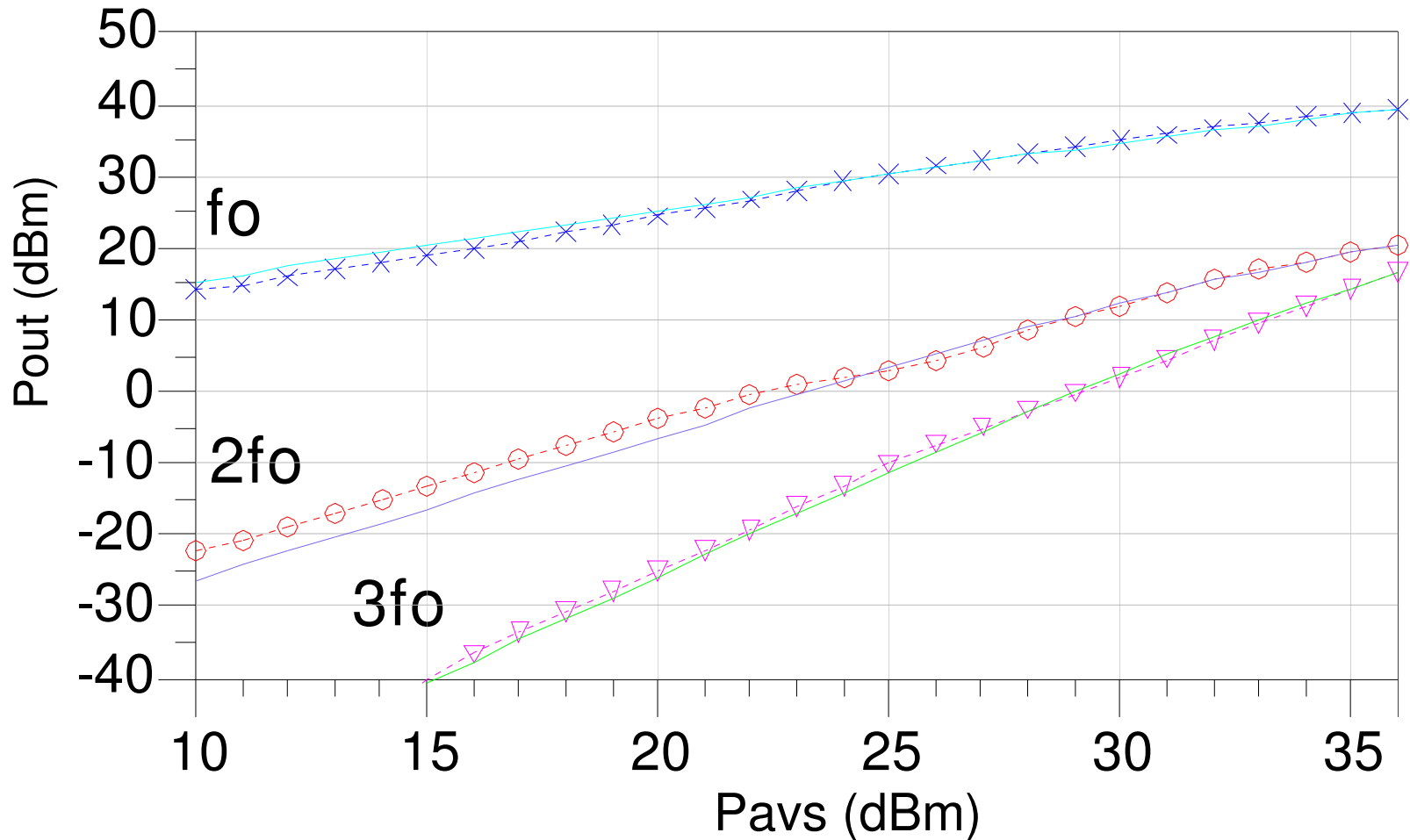


Harmonic Power Verification



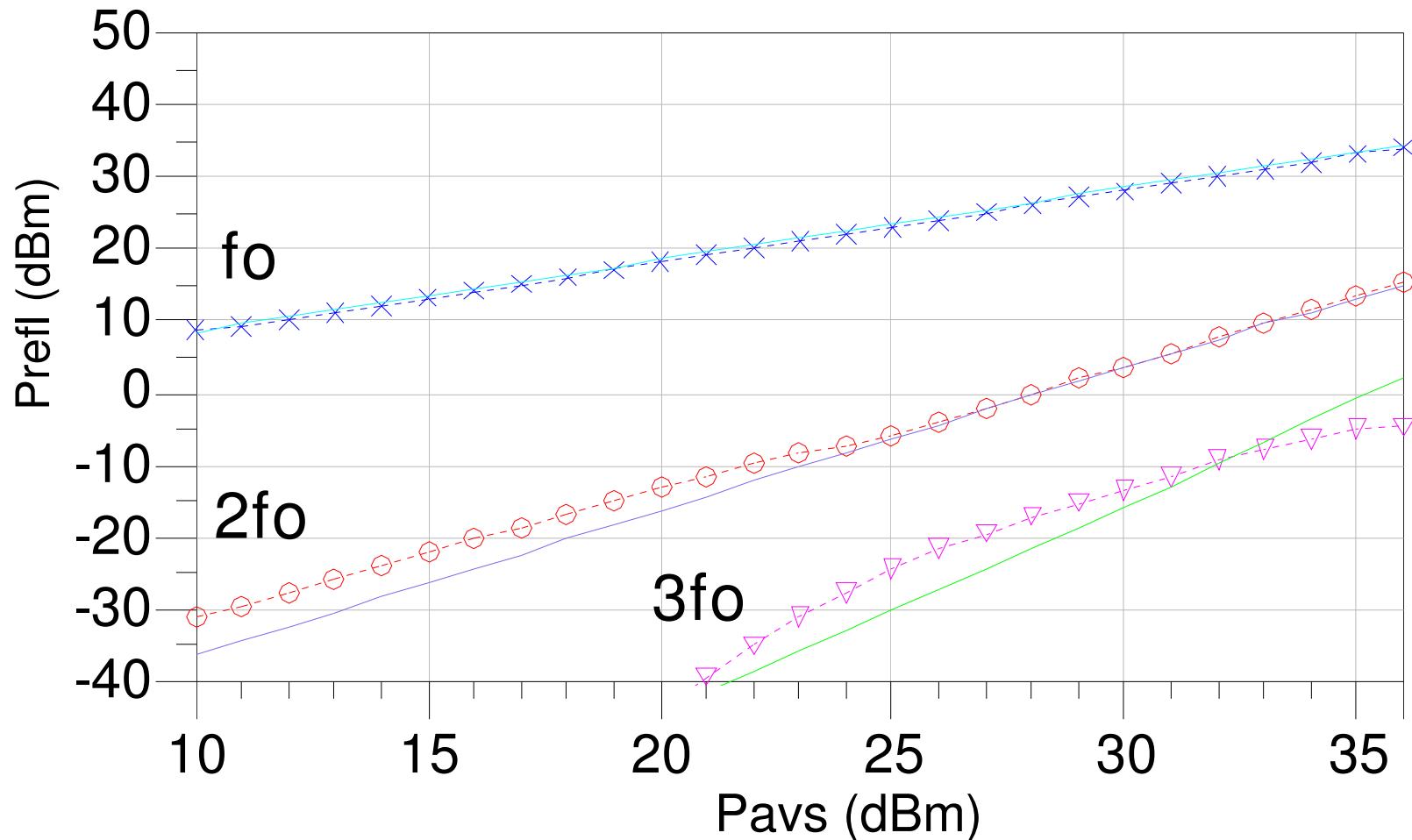
- Large signal measurement system
 - DUT driven at 2GHz from 10dBm to 36dBm
 - Output and input reflected power for three harmonics
- No impedance matching on DUT
 - Harmonic generation and power reflection
 - Generalized characterization using 50 Ohms terms

Output harmonic power



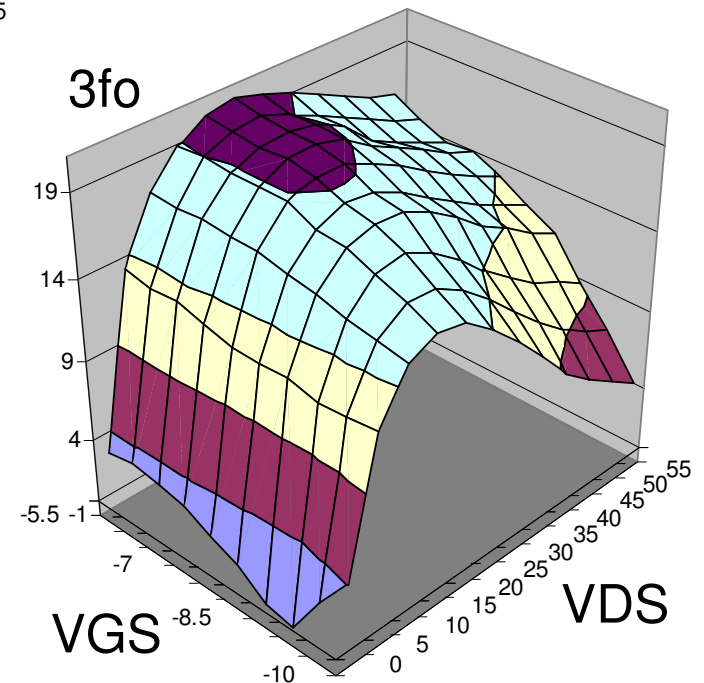
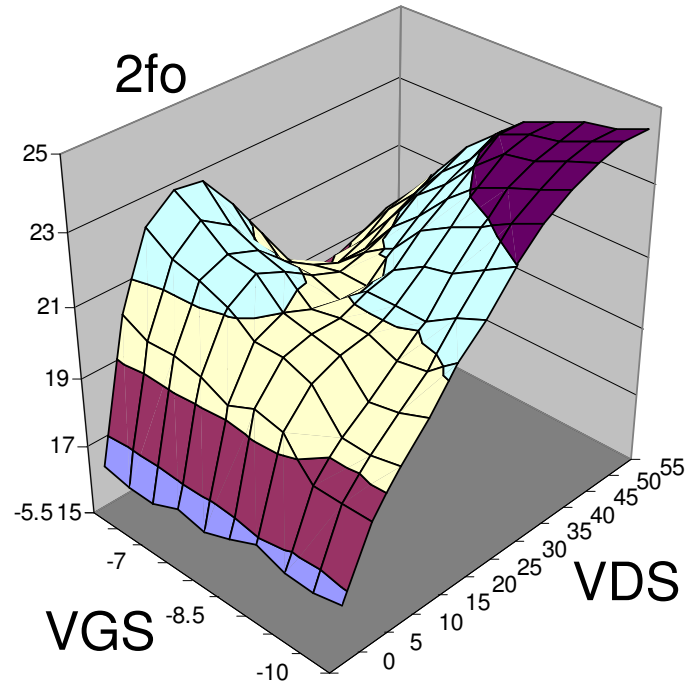
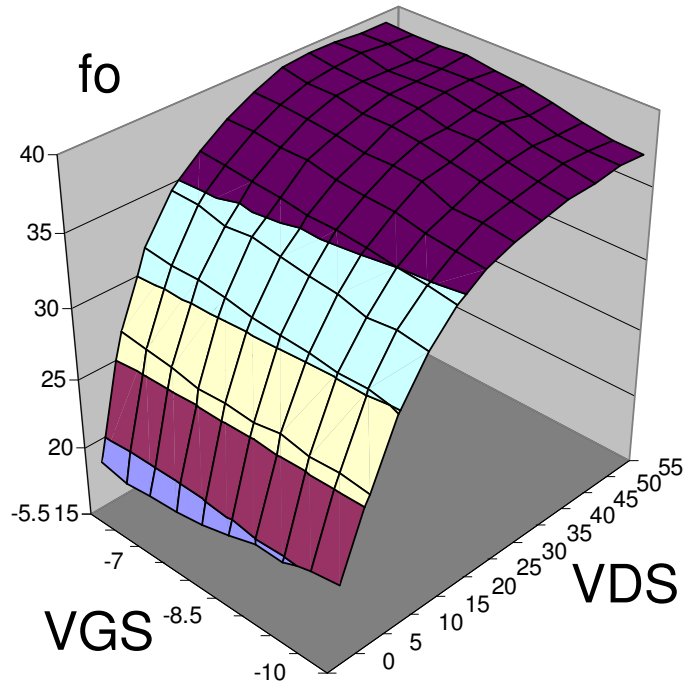
- Good agreement for three harmonics from 10dBm to 36dBm source power at 2.0GHz for DUT biased at $V_{DS}=48.0V$, $I_{DS}=500mA$
- Up to fundamental output power of 40dBm

Input reflected harmonic power



- Good agreement for three harmonics from 10dBm to 36dBm source power at 2.0GHz for DUT biased at $V_{DS}=48.0V$, $I_{DS}=500mA$
- Up to fundamental reflected power of 34dBm

Further Work - Harmonic Power



36dBm incident available source power

$V_{GS} = -10$ V to -5.5 V in 0.5 V steps

$V_{DS} = 0$ V to 55 V in 5 V steps

- Large signal power measurement over swept biases

Conclusions

- A new, simple empirical large-signal model for SiC MESFETs presented
- Mathematically versatile drain equation combining power series with Chalmer's model
 - Static IV
 - Pulsed IV
- Large-signal SiC MESFET model can predict
 - Pulsed IV characteristics
 - S-parameters without RF current generator
 - Large signal output and input reflected power for three harmonics

Acknowledgements

- Authors would like to thank the following people for their support and contributions to this work
 - Dr. Giovonnae Anderson
 - Dr. David McQuate
 - Dr. Wayne Martin

Development of our IV model

- Step 1: Take data
- Step 2: (Optional) Interpolate and extrapolate data if necessary
- Step 3: Take the derivative of I_{ds} wrt V_{gs} at every V_{ds} value. From this, find g_{mpk} , I_{pk} , V_{pk} at every V_{ds} .
- Step 4: Fit g_{mpk} , I_{pk} , V_{pk} wrt V_{ds} to a polynomial
- Step 5: Guess a set of P parameters at each V_{ds}
- Step 6: Optimize the P for every V_{ds} . In other words, fit I_{ds} vs V_{gs} curve for each value of V_{ds} .
- Step 7: Fit the optimized P parameters as polynomial functions wrt to V_{ds} .
- Step 8: Using the fitted parameters, compute the I_{ds} based on the polynomial fitted Angelov model